Krysdal Warhol

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Education

Peking University	**Beijing, China**
B.S. in Computer Science and Economics	*Sep. 2023 – June. 2027*

- **GPA:** 3.82/4.0
- **Core Courses:** Data Structure and Algorithm A (96), Introduction to Computer Systems (91), Computer Networks (96), Computer Architectures (90), Introduction to Computer Vision (94), Linear Algebra A (91), Discrete Mathematics (92), Probability Theory and Statistics (91), Intermediate Microeconomics (96), Intermediate Macroeconomics (97), Game Theory (94), International Trade (98)

Zhenhai High School of Ningbo	**Ningbo, China**
Innovation Class (47 members), Jiaochuan Academy (Class 2)	*Sep. 2020 – June 2023*

- Ranked Top 5 in academic performance multiple times within the school
- Recognized as Outstanding Graduate

Experience

Galbot Co., Ltd	**Beijing, China**
Research Intern	*Sep. 2025 – Present*

- Conduct research on Vision-Language-Action (VLA) models for robotic manipulation.
- Contribute to model architecture design integrating stereo vision and multimodal action learning.
- Participate in training and benchmarking billion-scale robotic action datasets.
- Currently working on a project about cross-embodiment.

Awards

National Scholarship	*Dec. 2025*
Yanchuang Capital Scholarship	*Dec. 2024*
Merit Student	*Dec. 2024, Dec. 2025*

Languages

Chinese: Mother Tongue	
English: Professional Working Proficiency	***TOEFL:** 107 (R:29/L:30/S:21/W:27)*
Japanese: Intermediate	***JLPT:** N4 passed*
Spanish: Basic	

Projects

StereoVLA: Enhancing Vision-Language-Action Models with Stereo Vision
S. Deng, M. Yan, Y. Zheng, J. Su, W. Zhang, X. Zhao, H. Cui, Z. Zhang, H. Wang
Submitted to Robotics: Science and Systems (RSS) 2026; arXiv:2512.21970

GraspVLA: a Grasping Foundation Model Pre-trained on Billion-scale Synthetic Action

Data
S. Deng, M. Yan, S. Wei, H. Ma, Y. Yang, J. Chen, Z. Zhang, T. Yang, X. Zhang, W. Zhang, H. Cui, Z. Zhang, H. Wang
Accepted to Conference on Robot Learning (CoRL) 2025; arXiv:2505.03233